The precession equations ( $u, v, w$ correspond to $\alpha, \beta, \gamma$ ) are

$$
\begin{align*}
& k u^{*}+H g_{1} v^{\circ}+H g_{2} w^{\circ}=0,  \tag{12}\\
& k v^{*}-H g_{1} u^{\circ}+H g_{3} w^{*}=0, \\
& k w^{*}-H g_{2} u^{*}-H g_{3} v^{*}=0
\end{align*}
$$

and for $k \neq 0$ and $\mu=H^{-1} \neq 0$ have the unique solution

$$
\begin{equation*}
u=\alpha_{0}, \quad v=\beta_{0}, w=\gamma_{0} \tag{13}
\end{equation*}
$$

If we divide Eqs. (11) by $H$, introduce the small parameter $\mu=H^{-1}$, integrate them, and retain only the principal terms in the general solution, then we have

$$
\alpha=\alpha_{0}+g_{3} E, \beta=\beta_{0}-g_{2} E, \gamma=\gamma_{0}+g_{1} E
$$

where

$$
E=\frac{g_{9} \alpha_{0}{ }^{\circ}-g_{2} \beta_{0}{ }^{\circ}+g_{1} \gamma_{0}{ }^{\circ}}{k\left(g_{1}{ }^{2}+g_{2}{ }^{2}+g_{3}{ }^{2}\right)}\left(1-e^{-k t}\right)
$$

This solution differs from solution (13) by terms nondepending on the small parameter $\mu=H^{-1}$; therefore, the passage from the full equations (11) to the precession equations (12) is inadmissible (in the example given $\operatorname{det} G=0$ ).

## REFERENCES

1. Merkin, D. R., On some general properties of material systems containing gyroscopes. Vestn. Leningradsk. Gos. Univ. , Ser. Matem. , Fiz. i Khimii, № 9, 1952.
2. Merkin, D.R., Gyroscopic Systems. Moscow, Gostekhizdat, 1956.
3. Merkin, D.R., On the stability of motion of a gyro gimbal. Inzh. Zh. MTT, $\mathrm{N}^{8} 5,1966$.
4. Tikhonov, A.N., Systems of differential equations containing small parameters in the derivatives. Matem. Sb. , Vol, 31 (73), N ${ }^{2} 3,1952$.
5. Wasow. W. . Asymptotic Expansions of Solutions of Ordinary Differential Equations. J. Wiley and Sons, Wiley-Interscience Series, N. Y., 1966.

Translated by N. H.C.
UDC 531.31

## INVARIANTS OF MULTDIMENSIONAL SYSTEMS WITH ONE RESONANCE RELATION

```
PMM Vol. 38, N` 2, 1974, pp. 233-239
    L. M. MARKHASHOV
    (Moscow)
    (Received September 18, 1973)
```

The description of invariants generated in systems of ordinary equations by homeomorphisms of a neighborhood of a singular point is connected both with stability problems $[1,2]$ as well as with the broader problems of the topological, analytical (or formal) classification of such systems [3,4]. If the eigenvalues of the system's linear part are related by only one resonance relation, a reduction to normal form [5] enables us to extend the results obtained in [6] to invariants of an $n$ th-order system [7]. Namely, we have shown that the group of all analytic
homeomorphisms of a neighborhood of a singular point generates in the equations' coefficient space $n h$ invariant sets depending upon the first $2 q h+1$ terms of the expansion of the right-hand sides ( $q$ is the order of the resonance, $h$ is the codimension of the system's degeneracy). Besides these the group can have only singular invariant sets (depending on all the system's coefficients).

1. Formulation of results. We examine $n$ th-order autonomous systems

$$
\begin{equation*}
\dot{x}=f(x), \quad f(0)=0 \tag{1.1}
\end{equation*}
$$

Here $f(x)$ is a vector-valued functions analytic in the neighborhood of the point $x=0$. The eigenvalues $\lambda_{i}$ of the linear part are related by the single resonance relation

$$
\begin{equation*}
\lambda_{1} n_{1}+\ldots+\lambda_{n} n_{n}=-0 \tag{1,2}
\end{equation*}
$$

There exists a unique formal power series

$$
\begin{equation*}
u=u_{q}+u_{q+1}+\ldots, u_{q}=x_{1}^{n_{1}} \ldots x_{n}^{n_{n}} \tag{1.3}
\end{equation*}
$$

satisfying the conditions:

1) resonance terms are absent in the difference $u-u_{q}$;
2) $L u \equiv \sum_{i=1}^{n} f_{i}(x) \frac{\partial u}{\partial x_{i}}=g_{h+1} u_{q}^{h+1}+g_{h+2} u_{q}^{h+2}+\ldots, \quad g_{h+1} \neq 0$

The number $h \geqslant 1$ is called the codimension of the degeneracy of system (1.1). The sign of the number $g_{h+1}$ determines the stability of the point $x=0$ in the critical cases of one zero root or of a pair of pure imaginary roots.

The group $G$ of all analytic homeomorphisms of a neighborhood of point $x=0$ generates a system of invariant sets in the space of coefficients of the expansion of $f(x)$. Let $\rho_{s}$ be the number of those of them which depend only on terms of order no higher than $s$ in the expansion of $f(x)$. The number $\rho_{s}$ does not decrease as $s$ grows, However, the following statement is valid.

Theorem. The number $\rho_{s_{0}}=\max \rho_{s}$ of invariant sets depending only of a finite segment of $f(x)$ is finite

$$
\rho_{s_{0}}=n h
$$

while the maximum order $s_{0}$ of this segment is determined by the formula

$$
s_{0}=2 q h+1
$$

These exhaust all invariant sets of formal transformations. Besides them the analytic group $G$ can have only singular invariant sets (depending on all coefficients of the expansion of $f(x)$ ) responsible for the convergence of the transformations.
2. Proof of the theorem. We do not detail the presentation of the stages in the proof because they are analogous to those in [6]. For an arbitrary power series $\xi_{k}=\Sigma c_{k_{1} \ldots k_{n}}^{(k)} x_{1}^{k_{1}} \ldots x_{n}{ }^{k_{n}}$ and for the operator $\bar{Z}=\Sigma \xi_{k} \partial / \partial x_{k}$ we set
2.1. Since a formal transformation of any analytic system to a normal form always
exists [5], the problem is equivalent to the classification of normal forms relative to the group $G$ of transformations preserving them. For an arbitrary element of $Z$ of the corresponding algebra $[L, Z]=0$. In particular $[L, Z]^{\circ} \equiv\left[L^{\circ}, Z^{\circ}\right]=0$. Hence

$$
\left.\left[L_{1}, Z_{l}{ }^{j}\right]=-\sum_{\alpha+\beta=l-1} \mid L_{\alpha}, Z_{i s}{ }^{2}\right]
$$

Since

$$
\left[L_{1}, Z_{l}^{\nu}\right]=v Z_{l}{ }^{\nu}\left(L_{1} \equiv \Sigma \lambda_{k} x_{k} \partial / \partial x_{k}\right)
$$

$Z_{l}{ }^{\nu}=0$ follows from $Z_{1}{ }^{\nu}=\ldots=Z_{l-1}^{\nu}=0$ when $v \neq 0$. Therefore, a normal form is preserved only by transformations with operators of the form $Z=Z^{\circ}$.
2.2. Series (1.3) is determined by the conditions $u^{\circ}=u_{14},(L u)^{\prime \prime}=0$ for all $v \neq 0$. Under the action of the normalizing transformation $x=x^{\prime}\left(1+(1)\left(x^{\prime}\right)\right)$, $\omega(0)=0$, the series $u$ and the operator $L$ are transformed, respectively, to $u^{\prime}$ and to the operator

$$
L^{\circ} \quad L_{1}+L_{q n+1}^{\circ}+\ldots+L_{n(m+1)+1}^{\circ}+\ldots
$$

in the normal form. Here $L u=L^{\circ} u^{\prime}$. We obtain

$$
(L u)^{\prime}=\left(L^{\circ} u^{\prime}\right)^{\nu}=L^{\circ} u^{\prime \nu}=0
$$

It is easy to find $u^{\prime}=u^{\prime \circ}$, where in the new variables $u^{\prime o}=u_{q}+\ldots \quad$ Further,

$$
L^{\circ} u^{\prime}=\left(L^{\circ} u^{\prime}\right)^{\circ}=(L u)^{\circ}=g_{h+1} u_{q}^{h+1}+\left.\ldots\right|_{x \rightarrow x^{\prime}}=g_{h+1} u_{q}^{h+1}+\ldots
$$

Hence we see that the numbers $h$ and $g_{h+1}$ are preserved under a normalizing transformation, Furthermore,

$$
\begin{align*}
& m \leqslant h  \tag{2,1}\\
& L^{\circ} u_{q}=L_{q(h+1)}^{\circ} u_{q}+\ldots=g_{h+1} u_{q}^{h+1}+\ldots \tag{2.2}
\end{align*}
$$

2.3. The operators we encounter subsequently form a series composed of operators of the form

$$
\begin{equation*}
Z_{q^{2}+1}=u_{q}^{\mu}\left(\alpha_{i, 1} x_{1} \frac{\partial}{\partial x_{1}}+\ldots+\alpha_{i, n} x_{n} \frac{\partial}{\partial x_{n}}\right) \equiv u_{q}^{\mu} Z_{1}\left(\alpha_{i \mu}\right) \tag{2.3}
\end{equation*}
$$

If $Z_{1}\left(\alpha_{\mu}\right) u_{q} \neq 0$, then $Z\left(\alpha_{\mu}\right) u_{q}=\beta u_{q}, \beta=\alpha_{i, 1} n_{1}+\ldots+\alpha_{\mu, n} n_{n}$ and the expansion

$$
\begin{aligned}
& Z_{1}\left(\alpha_{i^{\prime}}\right)=Z_{1}\left(\alpha_{\mu^{\prime}}\right)+\frac{\beta}{q} X_{1} \\
& Z_{1}\left(\alpha_{\mu^{\prime}}\right) u_{\eta}=0, \quad \mathrm{X}_{1}=x_{1} \frac{\partial}{\partial x_{1}}+\ldots+x_{n} \frac{\partial}{\partial x_{n}}
\end{aligned}
$$

holds. Consider $n$ linearly independent operators

$$
\begin{equation*}
X_{1}, Z_{1}\left(\alpha_{1}\right), \ldots, Z\left(\alpha_{n-1}\right) \quad\left(Z_{1}\left(\alpha_{k}\right) u_{q}=0\right) \tag{2.4}
\end{equation*}
$$

Any operator of form (2.3) can be written as a linear combination of them

$$
Z_{i \mu+1}=u_{i^{\prime}}{ }^{\prime}\left(\beta_{0} X_{1}+\beta_{1} Z_{1}\left(\alpha_{1}\right)+\ldots+\beta_{n-1} Z_{1}\left(\alpha_{n-1}\right)\right)
$$

Every operator $\quad Z_{(\mu)} \equiv Z_{q ; \beta+1}+Z_{q(\mu+1)+1}+\ldots$ satisfies the identity

$$
\left[L, Z_{(:)}\right]=\left[L,\left.Z\right|_{p q+1} ^{\circ}+[L, Z]_{q(p+1)+1}^{\circ}+\ldots\right.
$$

for some positive integer $p$. If the operators $Z_{q(\mu+1)+1}, Z_{q(\mu+2)+1}, \ldots$ are chosen such
that the number $p$ is maximal for the specified $Z_{q q_{1}+1}$, the operator $Z_{(\mu)}$ is said to be maximal and a positive integer $\tau=q(p-\mu)$ is associated to it. The next problem is to compute the numbers $\tau$ for all maximal operators whose formal expansions start with operators (2.4) multiplied by $u_{q}{ }^{\mu}, \mu=0,1, \ldots$ For operators $Z_{1}\left(\alpha_{k}\right)$ we trivially obtain $\left[L, Z_{1}\left(\alpha_{k}\right)\right]=0$, and, hence, $\tau=\infty$.
2.4. Consider the operator $X=X_{1}+X_{q+1}^{\llcorner }+X_{2 q+1}^{\circ}+\ldots$ We have

$$
\begin{aligned}
& {[L, X]_{k q+1}=0, \quad k<m} \\
& {[L, X]_{m q+1}=\left[L_{1}, X_{m q+1}^{\circ}\right]+\left[L_{m q+1}^{\circ}, X_{1}\right]=-m q L_{m q+1}^{\circ}}
\end{aligned}
$$

Consequently, $[L, X]=-m q L_{m \alpha+1}^{\circ}+\ldots$ independently of the choice of the operators $X_{l q+1}^{\circ}, k \geqslant 1$, so that $\tau=q m$ for the operator $X$. For operators of the form $X_{(\mu)}=u_{i}^{\mu} X_{1}+\ldots$ we have $\tau=q m$. In fact, independently of the chosce of $X_{q(\mu+1)+1}^{c}, \ldots,\left[L, X_{(\mu)}\right]=\left[L_{m q+1}^{\circ}, u_{q}^{\mu} X_{1}\right\rceil+\ldots=-m q u_{q}^{\mu} L_{i n q+1}+\ldots$
2. 5. Let us compute $\tau$ for operators of the form

$$
Z_{(\mu)}=u_{q^{\mu}}^{\mu}\left(\alpha_{1} x_{1} \frac{\partial}{\partial x_{1}}+\ldots+\alpha_{n} x_{n} \frac{\partial}{\partial x_{n}}\right) \ldots, \quad \alpha_{1} n_{1}+\ldots+\alpha_{n} n_{n}=0
$$

We denote

$$
\begin{align*}
& L=\varphi_{1}(u) x_{1} \partial / \partial x_{1}+\ldots+\varphi_{n}(u) x_{n} \partial / \partial x_{n}  \tag{2.5}\\
& \varphi_{k}(u)=\lambda_{k}+a_{k m} u^{m i n}+\ldots \\
& \left(a_{1!} n_{1}+\ldots+a_{n i} n_{n}=0, l<h \quad \text { by virtue of }(2.2)\right. \\
& Z_{(\mu)}=\psi_{1}(u) x_{1} \partial / \partial x_{1}+\ldots+\psi_{n}(u) x_{n} \partial / \partial x_{n} \\
& \psi_{h}(u)=\alpha_{k \mu} u^{\mu}+\ldots
\end{align*}
$$

We obtain

$$
\begin{aligned}
& {\left[L, Z_{(\mu)}\right]=\sum_{l}\left(\varphi \psi_{l}^{\prime}-\psi \varphi_{l}^{\prime}\right) u_{q} x_{l} \frac{\partial}{\partial x_{l}} \equiv \sum_{l} u_{i} x_{l} \Phi_{l} \frac{\partial}{\partial x_{l}}} \\
& \varphi=n_{\mathbf{1}} \varphi_{1}+\ldots+n_{n} \varphi_{n}, \quad \psi=n_{1} \psi_{l}+\ldots+n_{n} \psi_{n} \\
& \sum_{k} n_{k} \Phi_{k}=\varphi \psi^{\prime}-\psi \varphi^{\prime}
\end{aligned}
$$

Let $\sigma(f)$ denote the lowest power appearing in the expansion of $f$ in a power series (in $u$ ). From equality (2.5) it follows that

$$
\sigma\left(u \Phi_{k}\right) \leqslant \mu+2 h-m \quad \text { for } \quad \mu \neq m
$$

In fact,

$$
\sigma(\varphi)=h, \sigma\left(\varphi^{\prime}\right)=h-1, \sigma\left(\Phi_{k}\right) \geqslant \mu+h
$$

There exists $k$ such that $\sigma\left(\varphi \psi_{k}^{\prime}+\Phi_{h}\right)=h+\mu-1$. Further,

$$
\sigma(\psi)=\sigma\left(\frac{\varphi \psi_{h}^{\prime}-\Phi_{k}}{\varphi_{k}^{\prime}}\right) \leqslant h-m+\mu
$$

Hence, by virtue of the condition $\mu \neq m$

$$
\sigma\left(\Phi_{k}\right) \leqslant \sigma\left(\sum_{k} n_{k} \Phi_{k}\right)=\sigma\left(\psi \varphi^{\prime}-\varphi \psi^{\prime}\right)=2 h-m+\mu-1
$$

Consequently, $\sigma\left(u \Phi_{k}\right) \leqslant \mu+2 h-m$.
Let $\psi=c u^{\mu+h-m}+\ldots$. In order to obtain $\sigma\left(u \Phi_{h}\right)=\mu+2 h-m$ it is necessary that the equalities $\psi \varphi_{k}^{\prime}-\varphi \psi_{k}^{\prime}=0, k=1, \ldots, n$ be fulfilled up to order $2 h-m-1$ inclusive. In particular, the conditions

$$
m c a_{k m}-\mu b \alpha_{k m}=0 \quad\left(b=a_{1 h} n_{1}+\ldots+a_{i \hbar k} n_{n}\right)
$$

must be fulfilled. In other words, the operator for which $\tau=q(2 h-m)$ is determined uniquely. For other operators, being linearly independent with the ones indicated, the equalities $\alpha_{k m}=\lambda a_{k m}$ cannot be fulfilled for any $\lambda$ whatsoever. Consequently, for these operators $m c a_{k m}-\mu b \alpha_{k m} \neq 0$ and $\tau=q h$.

The functions $\Phi_{k}$ of maximal power $\mu+2 h-m$ are obtained in the following way. We define $\psi_{k}$ by the conditions

$$
u^{h} m_{\varphi_{1}}^{\prime}-\psi_{1}^{\prime}=(m-\mu) u^{2-i n-1} p^{p}, \quad u^{h-m_{i_{i}} p_{i}^{\prime}}-\psi_{n^{\prime}}^{\prime}=0, \quad k \geqslant 2
$$

Then $u^{\mu-m} \varphi^{\prime}-\psi^{\prime}=(m-\mu) u^{\mu-m-1} \varphi$, whence $\psi=u^{\mu-m} \varphi$. Therefore,

$$
\psi \varphi_{k}{ }^{\prime}-\varphi \psi_{k}{ }^{\prime}=\varphi\left(u^{\mu-1)} \varphi_{i}{ }^{\prime}-\psi_{k}{ }^{\prime}\right)=\delta_{i}{ }^{1}(m-\mu) u^{\mu-m-1} \varphi^{2}
$$

i. e. $\sigma\left(\psi \varphi_{k}{ }^{\prime}-\varphi \psi_{k}{ }^{\prime}\right)=\mu+2 h-m-1, k \geqslant 1$. Thus, when $\mu \neq m$ we have $\tau=q^{h}$ for all operators $Z_{(\mu)}=u_{q}^{\mu} Z_{1}+\ldots$ except one (which we denote $Y_{(\mu)}$ ). For the operator $Y_{(\mu)}$ we have $\tau=q(2 h-m)$.
2.6. Consider the case $\mu=m$.
2.6.1. If we choose $\psi_{k}^{\prime}=\varphi_{n}^{\prime}, k \geqslant 1$, then $\Phi_{k}=0, k \geqslant 1$, so that $\tau=\infty$ for the corresponding operator $\left(Y_{(m)}\right)$.
2.6.2. If $\psi_{k}^{\prime} \neq \varphi_{k}{ }^{\prime}$, then the first terms of the expansion of $\psi_{n}$ and $\varphi_{k}{ }^{\prime}$ cannot coincide since this leads to the maximal operator already considered in Sect. 2.6.1. Hence it follows that $\sigma\left(\psi \varphi_{k}{ }^{\prime}-\varphi \psi_{k}{ }^{\prime}\right)=\mu+h-1$ and, hence $\tau=q h$.
2.7. An ordered set of coefficients $a$ of polynomials of fixed degree $s$, being segments of expansions of $f(x)$, can be treated as coordinates of points of the Euclidean space $R_{s}$. We assume that the order ratio for $R_{s}$ and $R_{s+k}$ on a coinciding set of elements is the same. The infinite-dimensional linear space $R$ of all coefficients can be considered as the inductive limit of the sequence $R_{2}, R_{3}, \ldots$

The group $G$ of all analytic transformations of a neighborhood of point $x=0$, leaving this point in place and preserving the linear part of system (1.1), induces a group of transformations $G^{\prime}$ in $R: G^{\prime} \times R \rightarrow R$. The spaces $R$ are invariant relative to the transformations from $G^{\prime}$, while the collection of transformations from $G^{\prime}$ acting nonidentically in $R$ forms a Lie group $G_{s}{ }^{\prime}$. Let

$$
Z=\sum_{i} \xi_{i}(x) \frac{\partial}{\partial x_{i}}, \quad Z^{*}=Z+\sum_{k} \xi_{k}(a) \frac{\partial}{\partial a_{k}}
$$

be operators corresponding to one-parameter subgroups of groups $G$ and $G \times G^{\prime}$. The condition for the invariance of system (1,1) relative to the transformations from group $G \times G^{\prime}$ yiclds $\left[L, Z^{*}\right]=0$, or equivalently

$$
\begin{equation*}
[L, Z]=\sum_{i, k} \zeta_{k}(a) \frac{\partial f_{i}}{\partial a_{k}} \frac{\partial}{\partial x_{i}} \tag{2,1}
\end{equation*}
$$

Equality (2.6) is fulfilled identically with respect to $x$ and serves for the computation of the elements $\zeta_{k}^{j}(a)$ of the vector matrix $\left(\zeta_{k}{ }^{j}\right)$ of the algebra corresponding to
group $G^{\prime}$. This matrix has a block-triangular structure. If operator $Z$ is maximal, then in addition, all elements of its rows belonging to $\tau=q(p-\mu)$ nonzero blocks, vanish. Here it is impossible to increase this number with any linear combination of operator $Z$ with higher-order operators. The number $\rho_{s}$ of invariant sets generated by group $G^{\prime}$ in space $R_{s}$ is determined by the number of zero rows in the corresponding matrix $\left(\zeta_{k}{ }^{3}\right)_{s}$, i. e. by the number of maximal operators $Z_{(\mu)}$ for which simultaneously

$$
\begin{equation*}
q p+1>s, \quad q \mu+1 \leqslant s \tag{2.7}
\end{equation*}
$$

If system (1.1) is written in normal form from the very start, then $s=q s^{*}+1$, $s^{*}=0,1, \ldots$ Setting $\tau^{*}=p-\tau$, we write inequalities (2.7) as

$$
\begin{equation*}
s^{*}-\tau^{*}<\mu \leqslant s^{k} \tag{2.8}
\end{equation*}
$$

Let $r_{1}, r_{2}, r_{3}$ be the number of zero rows generated in the matrix $\left(\zeta_{k}^{j}\right)_{s}$ by the operators for which $\tau^{*}=m, h, 2 h-m$, respectively. From inequalities (2.8), with due regard to the preceding results, we obtain

$$
\begin{array}{ll}
r_{1}=m \\
r_{2}=(n-2) h & \left(s^{*} \geqslant m\right) \\
\left(s^{*} \geqslant h\right)
\end{array} \quad r_{3}=\left\{\begin{array}{l}
2 h-m \quad\left(2 h-m \leqslant s^{*}<2 h\right) \\
2 h-m+1 \quad\left(s^{*} \geqslant 2 h\right)
\end{array}\right.
$$

In the computation of $r_{3}$ we have taken into account that although $\mu>s^{*}-\tau^{*} \geqslant$ $2 h-(2 h-m)=m$, for $s^{*} \geqslant 2 h$, among the operators satisfying inequalities (2.8) we should include one more, namely, $Y_{(m)}$. The number of invariant sets is computed from the formula $\rho_{s}=r_{1}+r_{2}+r_{3}-1$ (the similarity transformation, not taken into account above, decreases the number of invariant sets by unity). Hence $\rho_{s_{0}}=n h$. From the formulas for $r_{i}$ we see that this number ceases to increase when $s^{*} \geqslant 2 h$. Consequently, $s_{0}=2 q h+1$.
3. Example. We examine a fourth-order system in normal form with a degeneracy codimension $h-1$

$$
\begin{align*}
& x_{i}^{*}=x_{i}\left(\lambda_{i}+a_{i 1} u+a_{i 2} u^{2}+\ldots\right), i \leqslant 4  \tag{3.1}\\
& u=x_{1}^{n_{1}} \ldots x_{4}^{n_{4}}, \lambda_{1} n_{1}+\lambda_{2} n_{2}+\lambda_{3} n_{3}+\lambda_{4} n_{4}=0
\end{align*}
$$

According to the theorem in this paper, system (3.1) has four invariants depending on segments of the right-hand sides of order not higher than $2 q+1$, i. e. on the coefficients $a_{11}, \ldots, a_{42}$. Let us find these invariants.

The components of the operators corresponding to one-parameter groups preserving the normal form of Eqs. (3.1) have the form (only the transformations affecting coefficients $a_{11}, \ldots, a_{42}$ ) are considered)
From the defining equations

$$
\xi_{i}=\alpha_{i} x_{i} u
$$

$$
\begin{aligned}
& \alpha_{i} x_{i} \sum_{j=0}^{\infty}\left(a_{i j}+n_{1} a_{1 j}+\ldots+n_{n} a_{n j}\right) u^{j+1}=\alpha_{i} x_{i} \sum_{j=0}^{n} a_{i j} u^{j+1}+ \\
& \quad x_{i} \sum_{j=0}^{\infty} j a_{i j} u^{j-1}\left(x_{1} n_{1}+\ldots+\alpha_{n} n_{n}\right)+x_{i} \sum_{j} \zeta_{i j}(c) u^{j}
\end{aligned}
$$

we find

$$
\zeta_{i, j+1}(a)=\alpha_{i}\left(n_{1} a_{1 j}+\ldots+n_{n} a_{n j}\right)-j a_{i j}\left(\alpha_{1} n_{1}+\ldots+\alpha_{n} n_{n}\right), \quad j=0,1, \ldots
$$

Hence, if we do not take the similarity transformation ( $\alpha_{1}=\ldots=\alpha_{n}=1$ ), into account, by the use of known standard procedures we find the following invariants:

$$
\begin{align*}
& a_{i 1}=\operatorname{Inv}, i=1,2,3,4  \tag{3.2}\\
& \omega_{1}\left[n_{3}\left(q^{*}-a_{31} q\right)+n_{4}\left(q^{*}-a_{41} q\right)\right]-\omega_{2}\left[n_{1}\left(q^{*}-a_{11} q\right)+n_{2}\left(q^{*}-\right.\right. \\
& \left.\left.\quad a_{21} q\right)\right]=\operatorname{Inv} \\
& \left(\omega_{1}=n_{1} a_{12}+n_{2} a_{22}, \omega_{2}=n_{3} a_{32}+n_{4} a_{2}, q^{*}=n_{1} a_{11}+\ldots+n_{n} a_{41}\right)
\end{align*}
$$

Thus, for $h=1$ and for one resonance relation (1.2), any analytic system of the fourth order can be reduced by a formal transformation to the form

$$
x_{i}=x_{i}\left(\lambda_{i}+a_{i 1} u+a_{i 2} u^{2}\right)
$$

where $a_{i_{1}}$ are fixed, while $a_{i_{2}}$ are related by the single condition (3.2).

## REFERENCES

1. Liapunov, A. M., General Problem of the Stability of Motion. Moscow-Leningrad, Gostekhizdat, 1950.
2. Chetaev, N. G., Stability of Motion, (English translation). Pergamon Press, Book № 09505, 1961.
3. Arnol'd, V.I., Ordinary Differential Equations. Moscw, "Nauka", 1971.
4. Reizin', L. E., Local Equivalence of Differential Equations, Riga, "Zinatne", 1971.
5. Briuno, A. D., Analytic form of differential equations. Tr. Mosk. Matem, Obshch., Vol. 25, 1971; Vol. 26, 1972.
6. Markhashov, L. M., Analytic equivalence of second-order systems for an arbitrary resonance. PMM Vol. 36, № 6. 1972.
7. Markhashov, L. M., Invariants of multidimensional systems with one resonance relation. Izv. Akad. Nauk SSSR, MTT, No 5, 1973.

Translated by N. H. C.
UDC 531.36

## ON THE STABILITY OF MOTIONS OF CONSERVATIVE MECHANICAL SYSTEMS UNDER CONTINUALLY-ACTING PERTURBATIONS

PMM Vol. 38, № 2, 1974, pp. 240-245
A. Ia.SAVCHENKO
(Donetsk)
(Received July 8, 1973)
We prove some theorems on the stability of motions of conservative mechanical systems under continually-acting perturbations, subject to specified constraints. In the investigation of stability of such type it is usually assumed only that the continually-acting perturbations are small [1]. Such a formulation omits from consideration an important class of conservative systems whose motions do not possess asymptotic stability because an integral invariant exists in them. However, in many problems concerning the structure of the continually-acting perturbations, certain information is available enabling us to estimate their influence

